	4.5 11.5 SW1 5 5 5 SW1 6 7 SW2	SW TRA 0.5 900- 900- 900- 900- 900- 900- 900- 900				
	SW1					м М П
P.C.B.MOUNTING DETAIL						
VERSION 深圳市百	可斯特电子有限公司	MODEL: EC11	I-152		DRAW	SCALE
A 0		DRAWING NO:				3:1
. ISSU. DATE 00 2014-09-01	REVISION ORIGINAL DRAWING	Design	TOL. UNLESS OTHERWIST BASIC DIMENSIONS	E SPEC. TOL.	СНКД	UNIT
01			$L \le 10$	$\pm 0.3$		mm
02			10 < L	± 0.5	APPD	
03			100 ≤ L	± 0.8		
04			ANGLE	± 5°		第1页

EC11 FORWARD DIRECTION SERIES SPECIFICATION 1. 一般事项General 1-1. 适用规格 Scope 本规格书适用于微小电流回路的电子设备,属11型回转型编码器. This specification applies to 11mm size low-profile rotary encoder (incremental type) for microscopic current circuits, used in electronic equipment. 1-2. 标准状态Standard atmospheric conditions 除另有规定外,测量应在以下状态下进行: Unless otherwise specified, the standard range of atmospheric conditions for making measurements and test is as following limits: 度 Ambient temperature : 15℃ to 35℃ 温 相对湿度 Relative humidity : 25% to 85% 气 压 Air pressure :86kpa to 106kpa 如果对在上述所提到的条件中所做的实测值有疑问的话,应使用以下条件进行测量: If doubt arises on the decision based on the measured values under the above-mentioned conditions, the following conditions shall be employed: 度 Ambient temperature : 20±1℃ 温 相对湿度 Relative humidity : 63% to 67% 气 压 Air pressure :86kpa to 106kpa 1-3. 使用温度范围 Operating temperature range :-30℃ to+80℃ 1-4.保存温度范围 : -40℃ to+85℃ Storage temperature range 图1 fig.1 2. 构造Construction -∞ DC 5V 2-1. 尺寸 Dimensions  $\leq 10 \mathrm{K} \Omega$ 10KΩ 🕻 Terminal A 见所附成品图 Refer to attached drawing Terminal B A 端 子 B 端 子 3. 额定值 Rating -///\ ~W~ Ao -0 B 3-1. 额定电压 10K Ω 10K Ω Encoder Rated voltage: DC 5V 0.01 µ F ⊥ 0.01µF 编码器 3-2. 最大额定电流(阻抗负载) Terminal C Maximum operating current (resistive load) C 端 子 77/7// 各相导线 Each lead: 0.5mA(Max 5mA; Min 0.5mA) 7/1/// 公共导线Common lead: 1mA (Max 10mA; Min 0.5mA) 4. 使用上的事项Application Notes 4-1. 避免储藏于高温潮湿及腐蚀的场所. 产品购入后尽可能在6个月内使用完. 拆包装后未使用完的剩余 产品需储藏于防潮防毒的环境下. Avoid storing the products in a place at high temperature, high humidity and in Corrosive gases. Please use this product as soon as possible with 6 months limitation. If any remainder left after packing is opened, please store it with proper moistureproofing, gasproofing etc. 4-2. 编码器信号的计算方法应将操作的速度,信号的取样时间及电子回路中的微电脑软体等考虑进去. The encoder pulses count method should be designed with taking operating speed, sampling time and esign of the microcomputer software into cosideration. 4-3. 此产品在定位点的输出波形参照(5-1),因此在设计软体时请留意其状态,推荐以A相位为参考基准。 With this products the detent position output consult fig. 5-1. Therefore make the A phase the reference at the soft ware design stage. Recommended that use A output signal for the reference. 4-4. 在设计时要考虑到杂讯, 建议使用R/C滤波电路, (图1) At design of the pulse count process. Using the C/R filter circuit is Recommended. (fig. 1) 4-5. 本产品请勿碰触到水,可能会导致输出波形的异常.

Care must be taken not to expose this product to water or dew to prevent possible problem in pluses output waveform.

## EC11正向系列规格书 EC11 FORWARD DIRECTION SERIES SPECIFICATION

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项目		条件		规格	
ITEM		CONDITIONS		SPECIFICATIONS	
	A、B两信号输出相位差,输出波形详细见(图2/3)(虚线表示带卡点装置的上擎子处位置)				
	2 Phase-different si				
	(The broken line sho				
	轴回转方向	信号		输出波形	
	Shaft rotati-	Signal	Output		
5-1. 输出信号	onal direction		图2 fig.2	图 3 fig. 3	
Output signal		A(A-C端子间)	OFF !		
format	顺时针方向	A (TerminalA-C)	ON		
	C. W	B(B-C端子间)	OFF		
		B (Termina1B-C)	ON		
		A (A-C端子间)			
	逆时针方向	A (TerminalA-C)	ON		
	C. C. W	B(B-C端子间)			
		B (Termina1B-C)	ON -	ON L	
			1	■15 个脉冲/360°(图2)	
5-2.分解能力	回转360°的输出脉冲线	数.	52	15pulses/360° (fig. 2)	
Resolution	Number of pulses in			□20个脉冲/360° (图3)	
	r i r			20pulses/360° (fig. 3)	
	下(图4)所示回路, 4	铀以360°/S的速度			
	Measurement shall be			VS.	
	Shaft rotational spe		Test circuit : (fi		
		图4 〈fig.4〉		图5 〈fig. 5〉	
			5V OFF		
	10KΩ	 ≥ \$10K	Ω 3.5V – +		
5-3. 开关特性	Terminal A		erminal B	$\Lambda^{-} = \Lambda^{-} = \Lambda^{-} $	
Switching	A 端 子 「		B端子 1.5V  /- /	(-╈  - \ ┿ \	
characteristics			ncoder		
		Terminal	t1		
		C端子			
	(注)编码0FF指输出。				
			the voltage is 3.5V	/ or more(fig.5).	
		压1.5V以下的状态		31 314	
Code-ON area : The area which the voltage is 1.5V or less (fig. 5).				5V or less (fig. 5).	
	编码从OFF→ON或ON→C				
5-3-1.振荡					
Chattering	间.应符合规定Specified by the signal's passage time from 1.5V to 3.5V of each switching position(code OFF~ON or ON~OFF)				
, i i i i i i i i i i i i i i i i i i i					
		会产生1mS以上,1.5V以下的ON部份.另外,如果各突跳			
5-3-2. 滑动杂讯	5-3-2. 滑动杂讯1.5V以下的范围在1mS以上时,则判定为另一个突跳.(突跳)SlidingSpecified by the time of voltage change exceed				
noise (Bounce)					
	-ON time less than 1mS between chattering (tlor				
t3) the voltage change shall be regarded as a part of					
	chattering. When the code-ONtime between 2 bounces is less than 1mS. they are regarded as 1 linked bounce.				
<u> </u>					

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	EC11 FORWARD DIRECTION SERIES SPECIFICATION						
5-3-3. 滑动噪音	编码OFF部份的电压变动。	3.5V以上					
Sliding noise	The voltage change in code-OFF area.	3.5Vmin					
	下(图6)所示回路,轴以360°/S的速度转动测定。						
	Measurement shall be made under the condition						
	which the shaft is rotated at 60r/min						
5-4. 相差位	Т	T1、T2、T3、T4≥0.08T					
Phase	A信号(A~C间) OFF	见图6 (fig.6)					
difference	signal A 图6 fig.6						
	B信号(B~C间)						
	signal B $T_1 T_2 T_3 T_4$						
	C.W Direction						
5-5. 绝缘阻抗	在端子和支架间施加电压 250V DC。						
Insulation	Measurement shall be made under the condition	100MΩ 以上					
resistance	which a voltage of 250V DC is applied between	$100M\Omega$ Min					
	individual terminals and frame.						
5-6. 耐电压	在端子和支架间施加AC300V电压1分钟	不得有绝缘破坏					
Dielectric	A voltage of 300V AC shall be applied for	Without arcing or breakdown.					
strength	1 minute between individual terminals and frame.						
	出力信号处于ON时安定状态条件下测定.	10以下					
	Measurement shall be stable condition which a	1ΩMax					
	output signal is ON.	44					
6. 机械性能 Mecha	nical Characteristics						
6-1. 全回转角度		360°(无止档点)					
Total ratational angle		360° (Endless)					
6-2. 定位点力矩	只适用于附卡点装置	2 ~ 15mN. m. (20 ~ 150gf. cm)					
Detent torque	Only suitable for C. C, equipment.						
6-3. 定位点数及位置	只适用于附卡点装置	■30点定位间隔角度12° ±2°					
Number	Only suitable for C. C, equipment.	30detents Step angle: $12^{\circ} \pm 2^{\circ}$					
and position		□20点定位间隔角度18°±2°					
of detent		20detents Step angle: $18^\circ \pm 2^\circ$					
6-4. 轴的推拉强度	在轴端,沿轴向施加 8Kg 的静负荷力推和拉各10秒钟	轴向虚位间隙0.4以内					
Push-pull	(产品焊锡固定在PCB上。)	Shaft play in axial					
strength of	Push and pull static load of 8Kg shall be	direction 0.4 Max					
shaft	applied to the shaft in the axial direction for						
51101 0	10s. (After soldering of the PC board)						
6-5. 端子强度	在端子的先端施加5N(500g)的力1分钟。	端子无损坏,无过度的松动.允许变形.					
Terminal	A static load of 5N (500g) be applied to the tip of	Without damage or excessive					
strength	terminals for 1 minute in any direction.	looseness of terminals. terminal					
		bend is permitted.					
6-6.轴套螺纹紧固强度		7. 0kgf. cm以上					
Bushing Nut		7. 0kgf. cm Min					
Tighten Strength							
<u>6-7.</u> 轴向间隙		0.4mm 以下					
Shaft play in axial		0. 4mm Max					
direction							
	在距离轴顶端5MM处,沿径向瞬间施加50mN.m(500gf.cm)的	0.7*L/30mm p-p 以下(L: 指					
6-8.轴摆动	力测试	安装平面到轴的柄端的距离.)					
Shaft wobble	A momentary load of 500gf.cm should be applied at the	0.7*L/30mm p-p Max					
	point 5mm from the tip of the shaft in a direction	L: Distance between mounting surface					
	perpendicular to the axis of shaft.	and measuring point on the shaft					
6-9. 轴的回转方向摆动	用角度板测定.	5°以下					
Shaft play	Testing by angle board.	5° Max					
in rotational							
wobble							
woootc							

## EC11正向系列规格书 EC11 FORWARD DIRECTION SERIES SPECIFICATION

7 耐久性能 Endura	EC11 FORWARD DIRECTION SERIES SPECIFICATION nce Characteristics	
项目	条件	规格
ITEM	CONDITIONS	SPECIFICATIONS
	在无负荷条件下轴以600~1000周/小时速度回转, 一日连续5000~8000次.	■在力矩≤100gf.cm时30,000±200周 30,000±200cycles per below 100gf.cm.
	The shaft of encoder shall be rotated at a speed of	□在力矩 > 100gf. cm时15,000±200周.
7-1. 回转寿命	$600 \sim 1000$ cycles/H without electrical load, after with	$15,000 \pm 200$ cycles per above 100gf. cm.
Rotational	measurements shall be made.	振荡 t1, t3≤5mS. 突跳 t2≤3mS.
life	(5000 to 8000 continuous cycles for 24 hours.)	尚余有轻微定位感.
		端子间接触阻抗200Ω以下
		Chattiring t1, t3 $\leq$ 5mS. Bounce t2 $\leq$ 3mS.
		Detent feeling has to remains
		Contact resistance 200ΩMax
	温度40±2℃,湿度90~95%的恒温恒湿槽中放置96±4	所有项应满足初期规格
	小时后,在常温、常湿中放置1.5小时后测试. The	Specifications in clause
7-2. 耐湿性	encoder shall be stored at temperature of 40 ±2°C	all items is shall be
Damp heat	with relative humidity of 90% to 95% for 96 $\pm$ 4H	satisfied.
	in a thermostatic chamber. And the encoder shall	
	be subjected to standard atmospheric conditions	
	for 1.5H, After which measurements shall be made.	28
	温度85±3℃的恒温箱中放置96±4小时,	所有项应满足初期规格。
	常温、常湿放置1.5小时后测试.	Specifications in clause
7-3. 耐热性	The encoder shall be stored at a temperature of	all items is shall be
Dry heat	$85 \pm 3$ °C for $96 \pm 4$ H in a thermostatic chamber. And	satisfied.
	then the encoder. shall be subjected to standard	
	atmospheric conditions for 1.5H, After which	
	measurements shall be made. 温度-40±3℃的恒温箱中放置96±4小时,	所有项应满足初期规格。
	常温、常湿放置1.5小时后测试.	所有灭应两足切朔风俗。 Specifications in clause
	The encoder shall be stored at a temperature of	all items is shall be
7-4.低温特性	$-40 \pm 3$ °C for $96 \pm 4$ H in a thermostatic chamber. And	satisfied.
Cold	then the encoder.shall be subjected to standard	
	atmospheric conditions for 1.5H, After which	
	measurements shall be made.	
	槽焊 Dip soldering.	不得有绝缘体的破损、变形、
7-5. 焊锡耐热性	使用基板: t=1.6mm的单面覆铜板.	接触无异常.
Resistance	Printed wiring board: single-sided copper clad	Electrical characteristics
to Soldering	laminate board with thickness of 1.6mm.	shall be satisfied No
heat	预热:基板表面温度100℃以下,时间1分钟以内.	mechanical abnormality.
	Preheating: 1. Surface temperature of board: 100℃.	
	or less 2. Preheating time: within 1 minute.	
	焊接:温度260±5℃或以下,时间3秒以内.	
	Soldering: Solder temperature: $260 \pm 5^{\circ}$ C or less	
	Immersion time:within 3S 手焊 Manual soldering.	
	于斥 Manual Soldering. 温度300℃以下,时间3秒以内.	
	Bit temperature of soldering iron: 300°Cless than	
	Application time of soldering iron: within 3S	
	端子在260℃±5℃温度的焊锡槽内浸锡3秒±0.5秒.	浸渍面须有75%以上焊锡附着
7-6.焊锡性	The terminals shall be immersed into solder bath	A new uniform coating of
Solderability	at 260℃for 3S±0.5S.	solder shall cover75% minimum
•		of the surface being immersed.

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IT	EC11 F0	RWARD DIRECTION S	ERIES SPECIFICATION			
推动开关部分Push	Switch Portion					
备注: 以下规格适用	于RE11编码器带开关系列	]	2. 2%			
Note: The following	Note: The following specification is only suitable for the one type with switch construction					
	of RE11 encoder series.					
1. 额定值 Rating						
1-1. 额定电压						
Rated voltage:1	DC 5V					
1-2. 最大额定电流(						
	面加贝報) ing current (resistive	load).10md Max				
	ical Characteris			Ir	1 14	
项目		条件		规格		
I TEM		CONDITIONS		SPECIFICATIONS		
2-1. 接触电阻	用DC 5V 1mA 电压测定.			$\leq 100 \text{m} \Omega$		
Contact	Voltage test at DC	5V 1mA.		$100m\Omega$ or less		
resistance	上山フィムルレーリン					
2-2. 绝缘阻抗	在端子和安装板间施加	- /				
Insulation	Measurement shall be			100MQ 以上		
resistance	which a voltage of 2.			100M $\Omega$ Min		
	individual terminals		plank.			
2-3. 振荡	以1秒钟1往返(0FF-0N-			≤ 10mS		
Bouncing	Shaft shall be push a		F-ON-OFF)	10mS or less		
2-4. 耐电压	在端子和安装板间施加,			不得有绝缘破坏		
Dielectric	A voltage of 300V AC			Without arcing or	breakdown.	
strength	between individual to	erminals and bus	hing and plank.			
3 机械性能 Mecha	nical Characterist	ics		1		
3-1. 开关电路				单极单投(按压ON)		
接点数				Single pole and single throw		
Switch circuit and				(push ON)		
number of pulse						
3-2.开关动作力	在轴端,沿轴向施加的按压力.					
Operation	Push static load to the shaft in the axial			500 ± 200gf		
fore of switch	direction				3.42	
3-3.开关移动量				■ 0. 5 ± 0. 3 mm		
Travel of switch				$\Box$ 1.5 ± 0.5 mm		
4 耐久性能 Endura	nce Characteristi	CS				
	在无负荷条件下沿轴向;		,以600次/小时	■20,000±200次.(	0.5行程)	
	<ul> <li>4-1.按压寿命</li> <li>Push-life</li> <li>b速度按压。</li> <li>Push 1Kgf to the shaft of encoder in the axial</li> <li>direction under non-load conditions, and with a speed</li> <li>of 600 times/hour.</li> <li>接触</li> <li>Cont</li> <li>Spece</li> </ul>			$20,000 \pm 200$ cycles. (0.5 Travel)		
				□15,000±200次.(1.5行程)		
4-1. 按压寿命				$15,000 \pm 200$ (1. $5114$ ) $15,000 \pm 200$ (1. 5 Travel)		
				接触电阻: ≤200mΩ. 其它应满足初期规格.		
				Contact resistance: $200m\Omega$ or less.		
				Specification in clause shall		
				be satisfied.		
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